



Updating of FBs OS V4.44

08/14/2006

- Modify the motion instruction FUN140(HSPO) to remove the bug -- while the motion parameter 9-0 (Rotation direction) was setting by 1 (while in forward pulse output, the current pulse value is deducting down; while in backward pulse output, the current pulse value is adding up), and the motion program worked in absolute coordinate, there existed the inconsistency between the target position and the current value of pulse
- Enhance the error detection about the serial port communication processing