

FUN 73 TSTC	Convenient instruction of PID temperature control for FB-2AJ(K)4/FB-2AH(T)4	FUN 73 TSTC
<div data-bbox="188 353 434 385" style="border: 1px solid black; display: inline-block; padding: 2px;">Program example 1</div> <div data-bbox="456 353 1412 421"> <p>The main unit is FBx-40MC(A) ,and 4 temperature modules of FB-2AK4 are attached.</p> <p>The settings of input span and polarity are all at 0~10V.</p> </div> <div data-bbox="188 443 1418 609"> <p>*** It takes only one FUN73 instruction to perform 16 points of PID temperature control when the temperature modules are identical in sensor type and the settings of input span and polarity are the same.</p> <p>*** When performing the FUN73 instruction of the first time, the system will automatically assign to each point its system default of gain (Kc), integral tuning constant (Ti), and derivative tuning constant (Td), etc. The user may change the settings if necessary.</p> </div> <div data-bbox="245 636 1423 2024"> <div style="display: flex; justify-content: space-between; align-items: flex-start;"> <div style="width: 65%;"> <ul style="list-style-type: none"> ● The status of M800~M831 are controlled by the MMI or external inputs to tell the status of sensor's installation; if it has the sensor, perform line broken detection, and not to perform the check if it hasn't. (It needs the retentive function, so M800~M1399 are the better choice). ● When temperature sensor installed (the corresponding bit of R4010 or R4011 is 1) and there is line broken of the sensor, the line broken value of that point will be displayed. ● When temperature sensor is not installed (the corresponding bit of R4010 or R4011 is 0), there will not perform the line broken detection; the temperature of that point is displayed 0. </div> <div style="width: 30%; border: 1px solid black; padding: 5px;"> <div style="text-align: center;">08D.MOV</div> <div style="display: flex; justify-content: space-between;"> EN <div> S : WM 800 D : R 4010 </div> </div> </div> </div> <div style="display: flex; justify-content: space-between; align-items: flex-start; margin-top: 20px;"> <div style="width: 65%;"> <ul style="list-style-type: none"> ● The status of M832~M863 are controlled by the MMI or external inputs to tell whether it needs the PID control of the corresponding point; perform the PID operation when the bit is ON, and not to perform if it is OFF (It needs the retentive function, so M800~M1399 are the better choice). ● When temperature control bit is ON (the corresponding bit of R4012 or R4013 is 1), FUN73 performs the PID operation of that point to obtain a suitable output signal. ● When temperature control bit is OFF (the corresponding bit of R4012 or R4013 is 0), FUN73 will not perform the PID operation of that point and output will be OFF. </div> <div style="width: 30%; border: 1px solid black; padding: 5px;"> <div style="text-align: center;">08D.MOV</div> <div style="display: flex; justify-content: space-between;"> EN <div> S : WM 832 D : R 4012 </div> </div> </div> </div> <div style="display: flex; justify-content: space-between; align-items: flex-start; margin-top: 20px;"> <div style="width: 65%;"> <div style="margin-bottom: 10px;"> M3 </div> <ul style="list-style-type: none"> ● When M3=ON, to measure the temperature of 13th (Sm=12) ~16th point of K-type thermocouple inputs and store the engineering values of measurement into R12~R15; also, store the primitive values into R3980~R3983. ● When there is line broken of the sensor, the value of line broken will be displayed. </div> <div style="width: 30%; border: 1px solid black; padding: 5px;"> <div style="text-align: center;">72.TP4</div> <div style="display: flex; justify-content: space-between;"> EN <div> Tp : 0 Pl : 0 Sm : 12 Ym: Y 40 AR: R 3851 TR: R 12 WR: R 240 </div> </div> <div style="display: flex; justify-content: space-between; align-items: center;"> ERR— ALM— </div> </div> </div> <div style="display: flex; justify-content: space-between; align-items: flex-start; margin-top: 20px;"> <div style="width: 65%;"> <div style="margin-bottom: 10px;"> M3 </div> <ul style="list-style-type: none"> ● When M3=ON, to measure the temperature of 9th (Sm=8) ~12th point of K-type thermocouple inputs and store the engineering values of measurement into R8~R11; also, store the primitive values into R3976~R3979. ● When there is line broken of the sensor, the value of line broken will be displayed. </div> <div style="width: 30%; border: 1px solid black; padding: 5px;"> <div style="text-align: center;">72.TP4</div> <div style="display: flex; justify-content: space-between;"> EN <div> Tp : 0 Pl : 0 Sm : 8 Ym: Y 32 AR: R 3848 TR: R 8 WR: R 230 </div> </div> <div style="display: flex; justify-content: space-between; align-items: center;"> ERR— ALM— </div> </div> </div> <div style="display: flex; justify-content: space-between; align-items: flex-start; margin-top: 20px;"> <div style="width: 65%;"> <div style="margin-bottom: 10px;"> M3 </div> <ul style="list-style-type: none"> ● When M3=ON, to measure the temperature of 5th (Sm=4) ~8th point of K-type thermocouple inputs and store the engineering values of measurement into R4~R7; also, store the primitive values into R3972~R3975. ● When there is line broken of the sensor, the value of line broken will be displayed. </div> <div style="width: 30%; border: 1px solid black; padding: 5px;"> <div style="text-align: center;">72.TP4</div> <div style="display: flex; justify-content: space-between;"> EN <div> Tp : 0 Pl : 0 Sm : 4 Ym: Y 24 AR: R 3845 TR: R 4 WR: R 220 </div> </div> <div style="display: flex; justify-content: space-between; align-items: center;"> ERR— ALM— </div> </div> </div> </div>		

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<p>*When total control points(Zh) of the FUN73 are greater than 4, it must be $Sh \geq Sm$ and the registers storing the current values (starting from TR) must be continuous.</p>		
<div> <div> <p>M3</p> <p>● When M3=ON, to measure the temperature of 1st (Sm=0) ~ 4th point of K-type thermocouple inputs and store the engineering values of measurement into R0~R3 and store the original values into R3968~R3971.</p> <p>● When completing the measurement of 1st ~16th point, it will perform the PID heating control of 16 (Zh) points from 1st (Sh=0) point to the 16th point.</p> <p>● R0~R15 : Registers of current engineering value .</p> <p>● Y48~Y63 : PID ON/OFF (PWM) output; it must be the transistor output.</p> <p>● R100~R115 : Registers of set point.</p> <p>● R120~R135 : Registers of deviation zone, it determines whether temperature falls in setting range. E.g. Set point is 200 and deviation zone is 5, then $195 \leq \text{Current value} \leq 205$ means the temperature is in zone.</p> <p>● R140~R155 : Setting point of gain (Kc).</p> <p>● R160~R175 : Setting point of integral tuning constant (Ti)</p> <p>● R180~R195 : Setting point of derivative tuning constant (Td).</p> <p>● R300~R315 : Output of PID calculation (value from 0~4095).</p> <p>● R200~R216 : Working registers.</p> </div> <div> <p>73.TSTC</p> <p>EN Tp : 0 Pl : 0 Sm : 0 Ym : Y16 AR : R3842 TR : R0 Yh : Y48 Sh : 0 Zh : 16 Sv : R 100 Os : R 120 PR : R 140 IR : R 160 DR : R 180 OR : R 300 WR : R 200</p> <p>ERR— AO0— AO1—</p> </div> </div>		
<div> <div> <p>M3</p> <p>● When M3=ON, M1000~M1015 tells the line broken status of corresponding sensor.</p> </div> <div> <p>43.NBMV</p> <p>EN S : R 200 Ns : 0 D : WM1000 Nd : 0</p> <p>43.NBMV</p> <p>EN S : R 220 Ns : 0 D : WM1000 Nd : 1</p> <p>43.NBMV</p> <p>EN S : R 230 Ns : 0 D : WM1000 Nd : 2</p> <p>43.NBMV</p> <p>EN S : R 240 Ns : 0 D : WM1000 Nd : 3</p> </div> </div>		
<div> <div> <p>M3</p> <p>● When M3=ON, M1016~M1031 tells the warning status of highest temperature warning or the heating circuit opened.</p> <p>● M1032~M1047 tells the status of temperature in zone.</p> </div> <div> <p>08.MOV</p> <p>EN S : R 210 D : WM1016</p> <p>08.MOV</p> <p>EN S : R 208 D : WM1032</p> </div> </div>		

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<p>Program example 2 The main unit is FBx-40MC(A) ,and 4 temperature modules of FB-2AH4 are attached. The settings of input span are all at 5V (the polarity are fixed at bipolar).</p> <p>*** It takes only one FUN73 instruction to perform 16 points of PID temperature control when the temperature modules are identical in sensor type and the settings of input span and polarity are the same.</p> <p>*** When performing the FUN73 instruction of the first time, the system will automatically assign to each point its system default of gain (Kc), integral tuning constant (Ti), and derivative tuning constant (Td), etc. The user may change the settings if necessary.</p>		
<ul style="list-style-type: none"> The status of M800~M831 are controlled by the MMI or external inputs to tell the status of sensor's installation; if it has the sensor, perform line broken detection, and not to perform the check if it hasn't. (It needs the retentive function, so M800~M1399 are the better choice). When temperature sensor installed (the corresponding bit of R4010 or R4011 is 1) and there is line broken of the sensor, the line broken value of that point will be displayed. When temperature sensor is not installed (the corresponding bit of R4010 or R4011 is 0), there will not perform the line broken detection; the temperature of that point is displayed 0. 		
<ul style="list-style-type: none"> The status of M832~M863 are controlled by the MMI or external inputs to tell whether it needs the PID control of the corresponding point; perform the PID operation when the bit is ON, and not to perform if it is OFF (It needs the retentive function, so M800~M1399 are the better choice). When temperature control bit is ON (the corresponding bit of R4012 or R4013 is 1), FUN73 performs the PID operation of that point to obtain a suitable output signal. When temperature control bit is OFF (the corresponding bit of R4012 or R4013 is 0), FUN73 will not perform the PID operation of that point and output will be OFF. 		
<p>M3</p>	<p>EN</p> <ul style="list-style-type: none"> When M3=ON, to measure the temperature of 13th (Sm=12) ~16th point of PT-100 RTD inputs and store the engineering values of measurement into R12~R15; also, store the primitive values into R3980~R3983. When there is line broken of the sensor, the value of line broken will be displayed. 	<p>08D.MOV—</p> <p>S : WM 800</p> <p>D : R 4010</p> <p>72.TP4—</p> <p>Tp : 2</p> <p>Pl : 3</p> <p>Sm : 12</p> <p>Ym: Y 40</p> <p>AR: R 3851</p> <p>TR: R 12</p> <p>WR: R 240</p> <p>ERR—</p> <p>ALM—</p>
<p>M3</p>	<p>EN</p> <ul style="list-style-type: none"> When M3=ON, to measure the temperature of 9th (Sm=8) ~12th point of PT-100 RTD inputs and store the engineering values of measurement into R8~R11; also, store the primitive values into R3976~R3979. When there is line broken of the sensor, the value of line broken will be displayed. 	<p>72.TP4—</p> <p>Tp : 2</p> <p>Pl : 3</p> <p>Sm : 8</p> <p>Ym: Y 32</p> <p>AR: R 3848</p> <p>TR: R 8</p> <p>WR: R 230</p> <p>ERR—</p> <p>ALM—</p>
<p>M3</p>	<p>EN</p> <ul style="list-style-type: none"> When M3=ON, to measure the temperature of 5th (Sm=4) ~8th point of PT-100 RTD inputs and store the engineering values of measurement into R4~R7; also, store the primitive values into R3972~R3975. When there is line broken of the sensor, the value of line broken will be displayed. 	<p>72.TP4—</p> <p>Tp : 2</p> <p>Pl : 3</p> <p>Sm : 4</p> <p>Ym: Y 24</p> <p>AR: R 3845</p> <p>TR: R 4</p> <p>WR: R 220</p> <p>ERR—</p> <p>ALM—</p>

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<p>*When total control points(Zh) of the FUN73 are greater than 4, it must be $Sh \geq Sm$ and the registers storing the current values (starting from TR) must be continuous.</p>		
	<div data-bbox="167 414 239 481">M3</div> <div data-bbox="199 548 1045 1086"> <ul style="list-style-type: none"> When M3=ON, to measure the temperature of 1st (Sm=0) ~4th point of PT-100 RTD inputs and store the engineering values of measurement into R0~R3 and store the original values into R3968~R3971. When completing the measurement of 1st ~16th point, it will perform the PID heating control of 16 (Zh) points from 1st (Sh=0) point to the 16th point. R0~R15 : Registers of current engineering value . Y48~Y63 : PID ON/OFF (PWM) output; it must be the transistor output. R100~R115 : Registers of set point. R120~R135 : Registers of deviation zone, it determines whether temperature falls in setting range. E.g. Set point is 200 and deviation zone is 5, then $195 \leq \text{Current value} \leq 205$ means the temperature is in zone. R140~R155 : Setting point of gain (Kc). R160~R175 : Setting point of integral tuning constant (Ti) R180~R195 : Setting point of derivative tuning constant (Td). R300~R315 : Output of PID calculation (value from 0~4095). R200~R216 : Working registers. </div>	<div data-bbox="1109 414 1300 817"> 73.TSTC Tp : 2 Pl : 3 Sm : 0 Ym : Y16 AR : R3842 TR : R0 Yh : Y48 Sh : 0 Zh : 16 Sv : R 100 Os : R 120 PR : R 140 IR : R 160 DR : R 180 OR : R 300 WR : R 200 </div> <div data-bbox="1300 414 1380 560"> ERR— AO0— AO1— </div>
	<div data-bbox="167 1243 239 1288">M3</div> <div data-bbox="199 1310 877 1366"> <ul style="list-style-type: none"> When M3=ON, M1000~M1015 tells the line broken status of corresponding sensor. </div>	<div data-bbox="1109 1243 1300 1377"> 43.NBMV S : R 200 Ns : 0 D : WM1000 Nd : 0 </div> <div data-bbox="1109 1388 1300 1523"> 43.NBMV S : R 220 Ns : 0 D : WM1000 Nd : 1 </div> <div data-bbox="1109 1534 1300 1668"> 43.NBMV S : R 230 Ns : 0 D : WM1000 Nd : 2 </div> <div data-bbox="1109 1680 1300 1814"> 43.NBMV S : R 240 Ns : 0 D : WM1000 Nd : 3 </div>
	<div data-bbox="167 1848 239 1892">M3</div> <div data-bbox="199 1915 885 2004"> <ul style="list-style-type: none"> When M3=ON, M1016 ~ M1031 tells the warning status of highest temperature warning or the heating circuit opened. M1032~M1047 tells the status of temperature in zone. </div>	<div data-bbox="1109 1848 1300 1915"> 08.MOV S : R 210 D : WM1016 </div> <div data-bbox="1109 1926 1300 2004"> 08.MOV S : R 208 D : WM1032 </div>